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This section of the documentation provides an overview of typical operations using a Fanuc robot to prepare a new program in RoboDK and transfer it to the robot. RoboDK supports all Fanuc robot controllers since RJ2, including RJ3, R-30iA and R-30iB. This documentation is based on the R-30iA Fanuc controller.

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How to write Karel programs? - Fanuc Robot Forum ...

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